

IR Remote Troubleshoot

Q1. The motors run even after the remote control input is stopped.

(A1) IR remote function will have some delay after switch is depressed so its not a problem. This is because the code says to take input 4 times in a loop. It's just a problem of demo code and not with Qu-bot. A good idea is to take the IR input, store it in a variable and compare the variable for motor driving.

You can program a modified file to solve this problem. Check Qu-bot "Downloads" section.